

receiving information that characterizes at least one machine-sensible feature of a target, said receiving step occurring substantially simultaneously with said sensing step; and

aiming a camera responsive to results of said sensing and/or said receiving step, wherein said sensing step includes sensing a gesture indicting a direction of said target.

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Sub B 12. A method of locating and displaying an image of a target, the method comprising the steps of:

scanning an area within the range of at least one sensor;

identifying potential targets;

storing information concerning machine sensible characteristics and locations of said possible targets;

sensing a triggering event, said triggering event generated by a human operator;

receiving information that characterizes at least one feature of said target, said receiving step occurring substantially simultaneously with said sensing step; and

aiming a camera responsive to results of said sensing, storing and/or said receiving steps, wherein said sensing step includes sensing a gesture indicting a direction of said target.

13. A method of aiming a camera at a target, comprising the steps of:

inputting an indication of a position of a target;

inputting further information about a machine-sensible characteristic of said target;

aiming a camera at said target responsively to said indication using said further information to reduce an error in said aiming, wherein said inputting an indication step includes inputting a gesture indicting a direction of said target.

14. A method of acquiring a target, comprising the steps of:

inputting spatial information to indicate a position of a target;

inputting further information about said target; and

orienting an instrument with respect to said target to acquire said target responsively to said spatial information while using said further information to reduce an ambiguity in said position, wherein said spatial information includes sensing a gesture indicting a direction of said target.